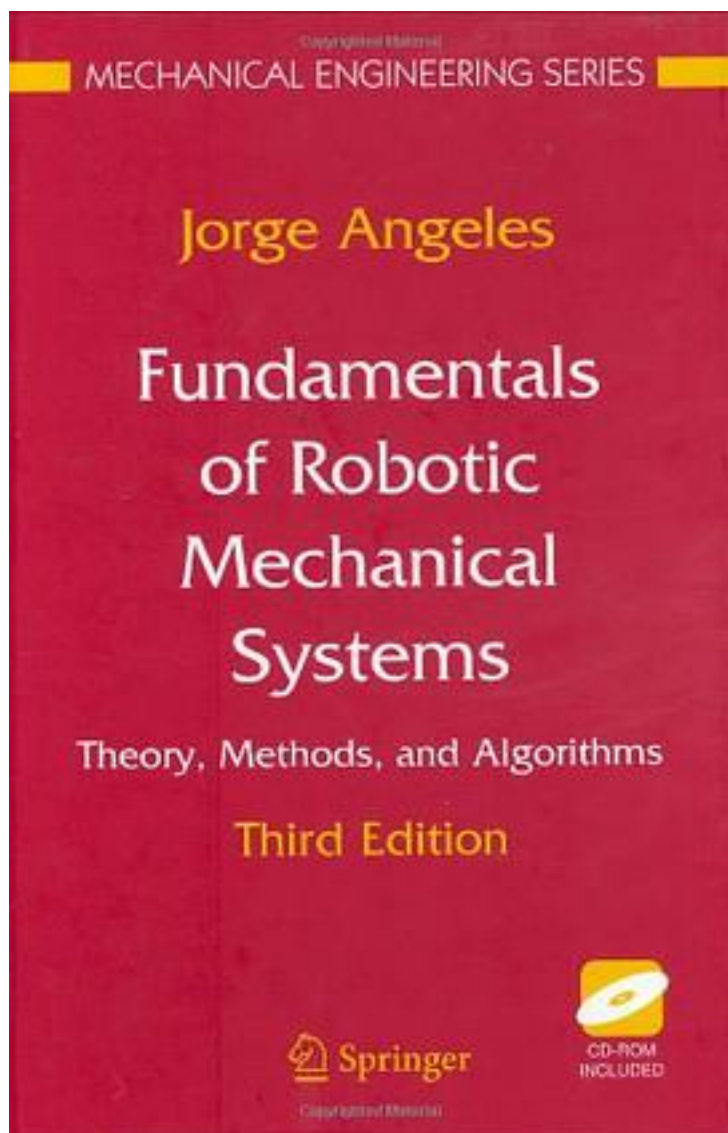


Fundamentals of Robotic Mechanical Systems



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This book deals with robots - such as remote manipulators, multifingered hands, walking machines, flight simulators, and machine tools - that rely on mechanical systems to perform their tasks. It aims to establish the foundations on which the design, control and implementation of the underlying mechanical systems are based. The treatment assumes familiarity with some calculus, linear algebra, and elementary mechanics; however, the elements of rigid-body mechanics and of linear transformations are reviewed in the first chapters, making the presentation self-contained. An extensive set of exercises is included and this new edition incorporates numerous advances.

作者介绍:

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标签

评论

课上老师给的参考书。唉，就不能给个中文的嘛。
这本书很多内容都默认学过数学专业的高等代数，读起来还是有点难度的。
没有读完，就这样吧，意思意思。

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书评

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