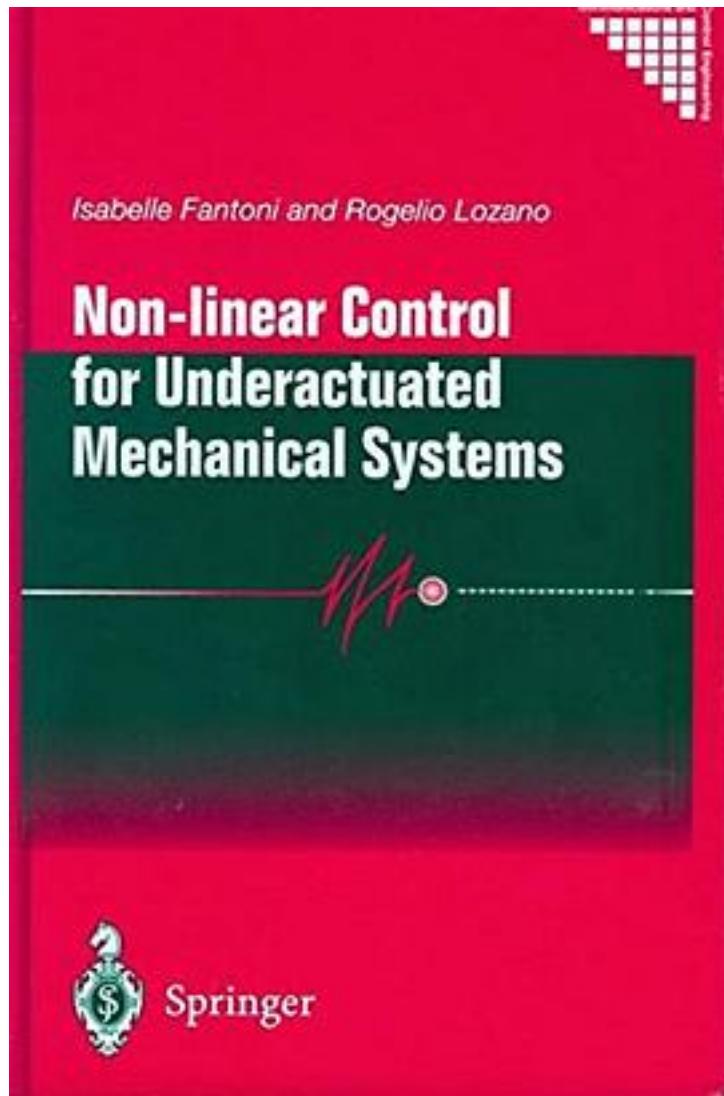


# Non-linear Control for Underactuated Mechanical Systems



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