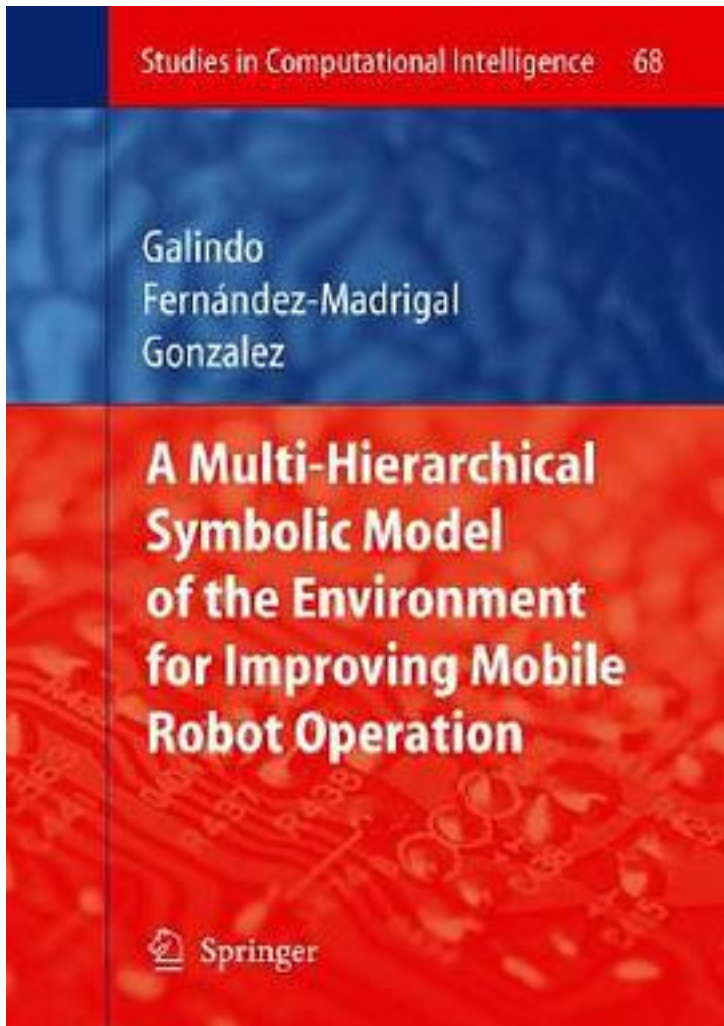


A Multi-hierarchical Symbolic Model of the Environment for Improving Mobile Robot Operation



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