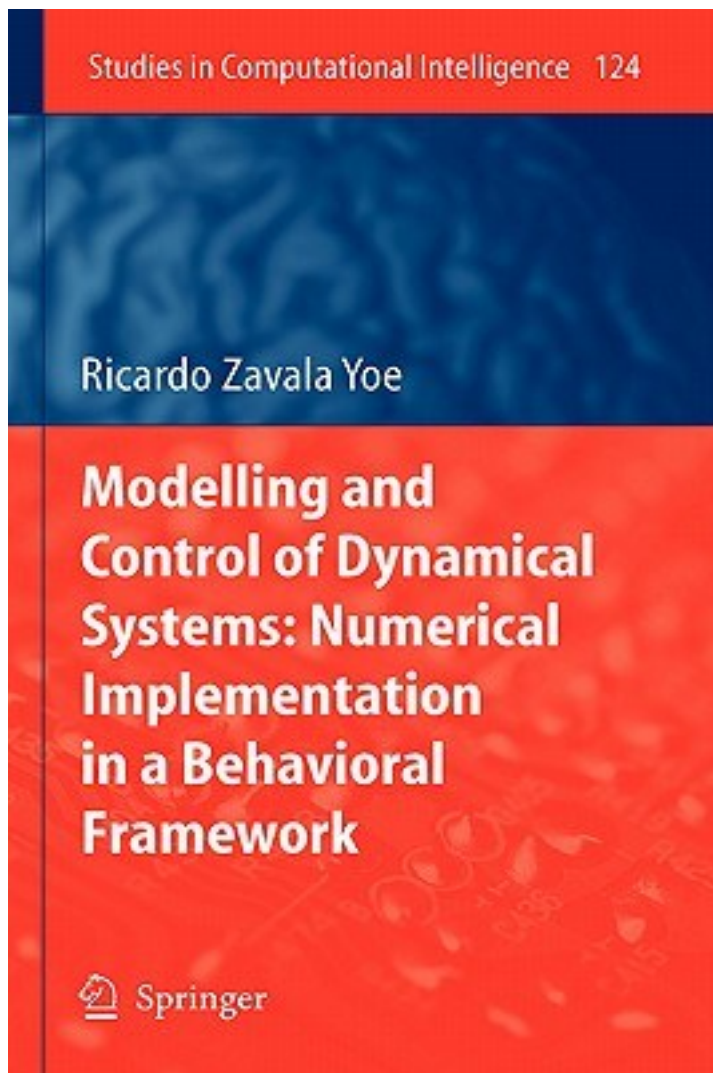


# Modelling and Control of Dynamical Systems



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著者:Yoe, Ricardo Zavala

出版者:

出版时间:

装帧:

isbn:9783540787341

作者介绍:

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