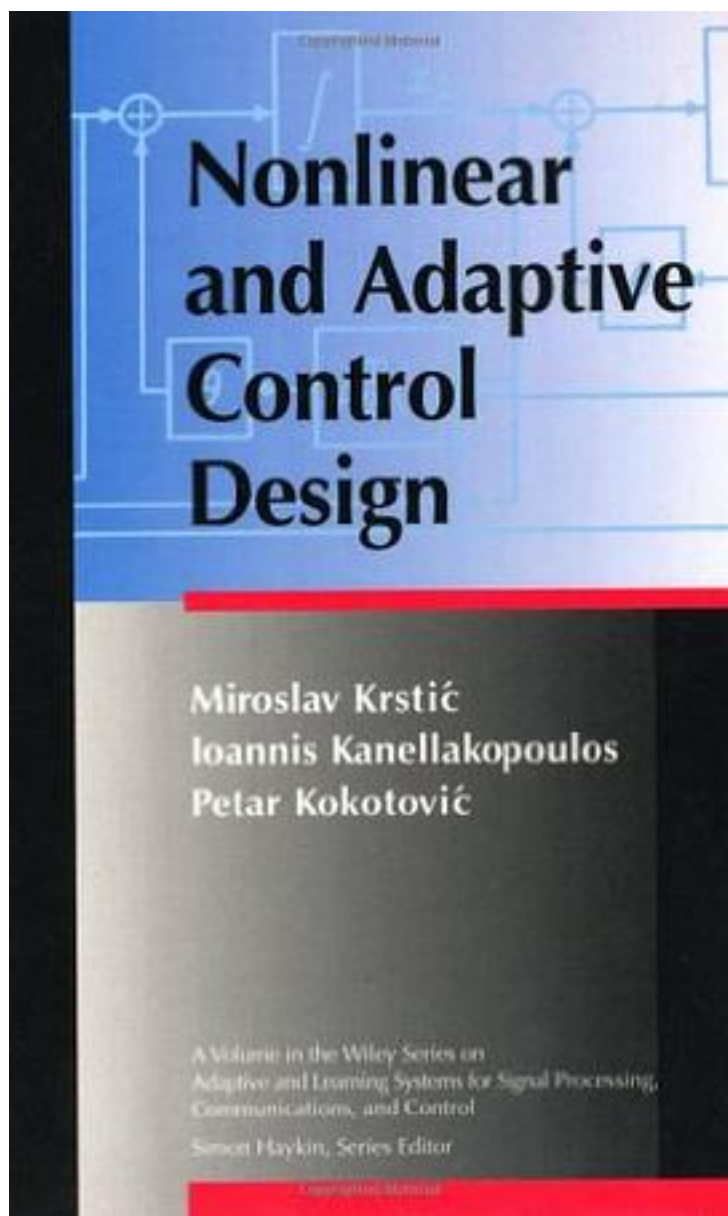


Nonlinear and Adaptive Control Design



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著者:Krstic, Miroslav/ Kanellakopoulos, Ioannis/ Kokotovic, Petar

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Using a pedagogical style along with detailed proofs and illustrative examples, this book opens a view to the largely unexplored area of nonlinear systems with uncertainties. The focus is on adaptive nonlinear control results introduced with the new recursive design methodology--adaptive backstepping. Describes basic tools for nonadaptive backstepping design with state and output feedbacks.

作者介绍:

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