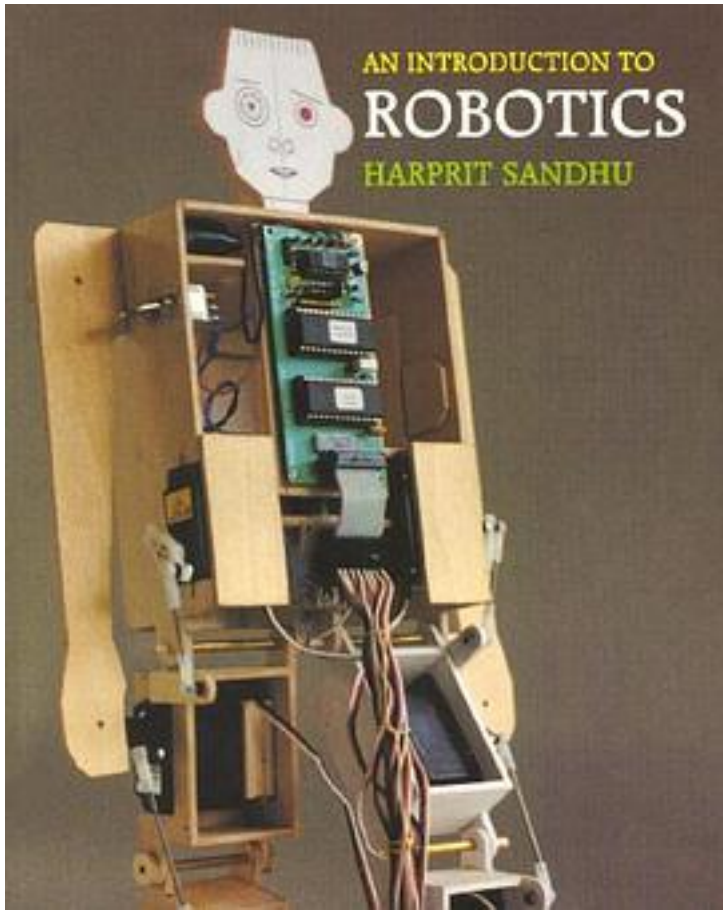


An Introduction to Robotics



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著者:Sandhu, H.S.

出版者:Special Interest Model Books

出版时间:1998-12

装帧:平装

isbn:9781854861535

This is an introduction for the amateur to the ideas and concepts, both theoretical and practical, of robotics. It is divided into two sections. The first covers how and why robots work and how they are controlled. The second discusses how to make a simple two-legged humanoid robot that can be programmed to walk. There are no

complicated formulae or equations to grapple with or complicated circuit diagrams to decipher, and you do not have to be a machinist or a programmer. The robot can be built quickly on a workbench or even a kitchen table, with a minimum number of handtools, and all the parts are easily available.

作者介绍:

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